

# Numerical solution of natural convective heat transfer in parabolic enclosures

S. O. TALABI and U. NWABUKO

Mechanical Engineering Department, University of Lagos, Lagos, Nigeria

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**Abstract**—Laminar free convective heat transfer within parabolic enclosures has been investigated using numerical computation methods. The geometry is a long cavity made up of a parabolic wall bowed over a horizontal wall. Due to symmetry, the analytical model is one-half of a two-dimensional cross-section consisting of a hot parabolic upper-wall, a cold horizontal base and an adiabatic vertical wall. Two cases of heat input from the parabolic upper-wall have been considered, namely (i) isothermal condition on the hot wall, and (ii) constant heat-flux through the hot wall. The base and vertical walls are made isothermal and adiabatic, respectively. A finite difference technique called ‘staggered differencing’ (SD) for both regular and irregular boundaries is applied in the iterative solution of the mass, momentum and energy equations. Steady state solutions have been obtained for the heat transfer to the cold base in the form of local and mean Nusselt numbers for  $0.05 \leq H/B \leq 1.0$ ,  $0 \leq Gr_B \leq 10^3$ ,  $0.73 \leq Pr \leq 20$  and  $0 < C_{fi} \leq 0.33$ . Results show that in case (i) the heat transfer rate to the cold wall increases with increase in  $Gr$  and  $Pr$  but decreases with increase in  $H/B$  and  $C_{fi}$ , except for an anomaly for  $C_{fi} = 0.33$ , i.e. the circular profile. In case (ii), the heat transfer rate increases with increase in  $Gr$ ,  $H/B$ ,  $Pr$  and  $C_{fi}$ .

## INTRODUCTION

STUDIES of laminar free convection in parabolic enclosures may be readily appreciated in consideration of the following two applications: (i) roofing-design of buildings for efficient air conditioning and (ii) design of efficient solar stills.

With respect to the former, roofing-designs are usually based on gross empirical formulations that are more suited to flat-top roofing than the more common pitched top, or the less common curved-top. Fundamental theoretical investigations that would really explain the intricate heat-transfer phenomena in the various roofings are often bypassed. Recently, however, there has been quite a few research studies akin to the heat transfer phenomena in flat-roofs as modelled by rectangular cavities, and to pitched-roofs as modelled by triangular cavities. Free convective heat transfer in rectangular cavities include the works of Poots [1], Davis [2], Newell and Schmidt [3], MacGregor and Emery [4], Elder [5] and Yin *et al.* [6]. Studies on triangular cavities include those of Akinsete and Coleman [7] and Flack and Witt [8]. These studies, some of which have been both theoretical and experimental, have enhanced the scientific knowledge of the heat transfer processes in the triangular and rectangular roofing types. Nevertheless, quite a few buildings have curved (parabolic) tops. These are often found in green houses, industrial buildings, arenas, nuclear power plants and houses in extreme-temperature regions of the world.

With respect to the second area of application, i.e. solar stills, most are designed in the form of plain glass or plexiglas placed horizontally or inclined over sets of heat absorbers, as elaborated by Edwards [9].

A clock-work mechanism is sometimes incorporated to rotate the collectors as the sun moves across the sky. However, a curved (convex) surface not only collects sun-rays from over a much wider range, but also concentrates the rays better than does a plain surface. A parabolic-surface collector, therefore, could operate effectively without a tilting mechanism, once it is properly installed.

Analytic studies of natural convection within concentric cylinders and spheres include the works of Powe *et al.* [10], Mack and Bishop [11], Mack and Hardee [12], Carley *et al.* [13] and Hodonett [14] while experimental studies include those of Scanlan *et al.* [15], Weber *et al.* [16] and Pneuili [17].

The present research is thus primarily aimed at the following two objectives: (i) to determine the free convective heat transfer characteristics for regions within curved roof-tops, and (ii) to find possible optimum surface curvatures for the design of solar collectors.

## MATHEMATICAL FORMULATION

### Analytical model

The analytical model consists of a two-dimensional cross-section of a roof which is infinite along its axis (Fig. 1(a)). Due to symmetry, the half-problem is used in the analytical formulation as a domain bounded above by a parabolic hot wall, HB, a horizontal cold wall, OB and an adiabatic wall, OH (Fig. 1(b)).

### Governing equations

The fluid within the cavity is assumed to be inviscid, incompressible, Newtonian with constant properties.

**NOMENCLATURE**

<i>A</i>	area of parabolic enclosure	<i>v</i>	<i>y</i> -component of velocity [m s <sup>-1</sup> ]
<i>b</i>	variation parameter of parabola (Fig. 1(b))	<i>V</i>	dimensionless velocity in <i>y</i> -direction.
<i>B</i>	characteristic length = model base length [m]	Greek symbols	
<i>C<sub>fi</sub></i>	concavity factor = ratio of area HBS to area HBO (Fig. 1(b))	$\alpha$	coefficient of thermal diffusivity [m <sup>2</sup> s <sup>-1</sup> ]
<i>C<sub>p</sub></i>	specific heat capacity at constant pressure [J kg <sup>-1</sup> K <sup>-1</sup> ]	$\beta$	coefficient of volume expansion [°C <sup>-1</sup> ]
<i>g</i>	gravitational acceleration [m s <sup>-2</sup> ]	$\theta$	dimensionless temperature, (T - T <sub>c</sub> )/(T <sub>H</sub> - T <sub>c</sub> ) or (T - T <sub>c</sub> )/(q <sub>n</sub> B/k)
<i>Gr</i>	Grashof number, (gβΔTB <sup>3</sup> /ν <sup>2</sup> )	$\mu$	dynamic viscosity [N s m <sup>-2</sup> ]
<i>h</i>	heat transfer coefficient [W m <sup>-2</sup> K <sup>-1</sup> ]	$\nu$	kinematic viscosity [m <sup>2</sup> s <sup>-1</sup> ]
<i>H</i>	height of parabolic enclosure [m]	$\phi$	general function for field variables
<i>i</i>	generalised node point	$\psi$	stream function [m <sup>2</sup> s <sup>-1</sup> ]
<i>k</i>	coefficient of thermal conductivity [W m <sup>-1</sup> K <sup>-1</sup> ]	$\Psi$	dimensionless stream function
<i>M</i>	total number of nodes in a grid system	$\omega$	vorticity [s <sup>-1</sup> ]
<i>Nu<sub>x</sub></i>	local Nusselt number, hx/k	$\Omega$	dimensionless vorticity.
<i>Pr</i>	Prandtl number, ν/α = μC <sub>p</sub> /k	Subscripts	
<i>q</i>	heat flux [W m <sup>-2</sup> ]	<i>c</i>	cold wall
<i>T</i>	temperature [°C]	<i>B</i>	based on characteristic length, <i>B</i>
<i>u</i>	<i>x</i> -component of velocity [m s <sup>-1</sup> ]	<i>H</i>	hot wall
<i>U</i>	dimensionless velocity in <i>x</i> -direction	<i>n</i>	normal direction
<i>U*</i>	characteristic velocity scale, νGr <sup>1/2</sup> /B	<i>w</i>	wall condition
		<i>x</i>	local value at <i>x</i> .

The flow field is two-dimensional with negligible viscous dissipation. Introducing the dimensional characteristic variables such that

$$X = \frac{x}{B}, \quad Y = \frac{y}{B}, \quad U = \frac{u}{U^*}, \quad V = \frac{v}{U^*},$$

$$\theta = \frac{T - T_c}{T_H - T_c} \quad \text{or} \quad \frac{T - T_c}{q_n B/k}$$

$$\Psi = \frac{\psi}{U^* B} \quad \text{and} \quad \Omega = \frac{\omega B}{U^*}$$

$$\frac{\partial^2 \Omega}{\partial X^2} + \frac{\partial^2 \Omega}{\partial Y^2} - Gr^{1/2} \left( U \frac{\partial \Omega}{\partial X} + V \frac{\partial \Omega}{\partial Y} \right)$$

$$- Gr^{1/2} \frac{\partial \theta}{\partial X} = 0 \quad (1)$$

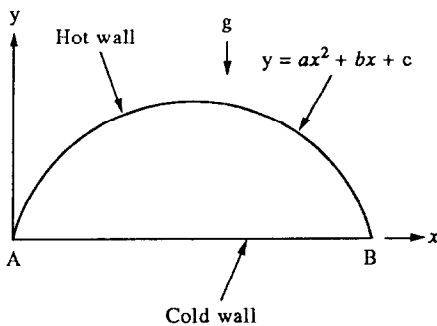
$$\frac{\partial^2 \theta}{\partial X^2} + \frac{\partial^2 \theta}{\partial Y^2} - Pr Gr^{1/2} \left( U \frac{\partial \theta}{\partial X} + V \frac{\partial \theta}{\partial Y} \right) = 0$$

$$(2)$$

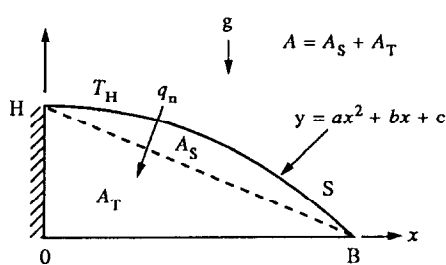
where

$$U = \frac{\partial \Psi}{\partial Y} \quad (3)$$

in the conservation equations, there results the following dimensionless equations:



(a) The full problem



(a) The half problem

FIG. 1. Analytical models of the physical problem.

$$V = -\frac{\partial\Psi}{\partial X} \tag{4}$$

and

$$\frac{\partial^2\Psi}{\partial X^2} + \frac{\partial^2\Psi}{\partial Y^2} + \Omega = 0. \tag{5}$$

Equation (1) is obtained from the  $X$ - and  $Y$ -components of the momentum equation after eliminating the pressure terms by cross-differentiation. The above set of equations is subject to the following boundary conditions:

$$U = V = 0, \text{ at all walls} \tag{6a}$$

$$\Psi = 0, \text{ at all walls} \tag{6b}$$

$$\theta = 0, \text{ at the cold wall} \tag{7a}$$

$$\frac{\partial\theta}{\partial X} = 0, \text{ at the adiabatic wall} \tag{7b}$$

$$\theta = 1, \text{ at the hot wall (Case I)} \tag{8a}$$

$$\frac{\partial\theta}{\partial n} = -1, \text{ at the hot wall (Case II)} \tag{8b}$$

$$\frac{\partial V}{\partial x} - \frac{\partial U}{\partial Y} = \Omega \text{ at all walls} \tag{9}$$

where  $n$  is the direction normal to the curved hot surface.

*Geometric parameters*

The theoretical analysis considers a generalised parabolic profile. However, the numerical computations require some parameters to characterise the physical variations of the enclosure. For this purpose, the height-to-base ratio,  $H/B$  characterises the size of the domain while the concavity factors,  $C_{fi}$  characterise the profile, i.e. the size of bulge (Fig. 1(b)).

*Irregular boundaries*

The parabolic hot wall creates the problem of irregular boundary in the application of the finite difference numerical solution technique. This makes it very difficult to deal with the Neuman-type of boundary condition. Moreover, high Grashof number range of solutions require large number-of-nodes in the discretisation process. The resultant effect is that the application of special routines as prescribed by Smith [18] and Carnahan *et al.* [19] for the computation of derivatives at normalised boundary nodes becomes rather tedious.

This problem is overcome by normalising all the irregular boundary nodes and applying the staggered differencing (SD) computational technique due to Nwabuko [20].

When the differential equations for the field variables (equations (1)–(3)) are cast into the SD form, they acquire the following general format:

$$\sum_{j=0}^4 A_{ij}\Phi_j = D_i, \quad i = 1, 2, \dots, M$$

i.e.

$$A_{i0}\Phi_0 + A_{i1}\Phi_1 + A_{i2}\Phi_2 + A_{i3}\Phi_3 + A_{i4}\Phi_4 = D_i$$

$$i = 1, 2, \dots, M \tag{10}$$

where,  $\Phi$  is a general function representing a field variable such as  $\theta$ ,  $\Psi$  and  $\Omega$ . The coefficients of  $\Phi$ , i.e. the  $A_{ij}$ s, depend on the particular variable being considered where, at a given point,  $i = j = 0$  when the referenced local node corresponds to the global node under computation (Fig. 2). For example, when the energy equation (2) is considered, the coefficients of  $\theta$  are given as

$$\left. \begin{aligned} A_{i0} &= (\gamma_0 + \delta_0 - \alpha_0 Pr GU_i - \beta_0 Pr GV_i) \\ A_{i1} &= (\gamma_1 + \alpha_1 Pr GU_i) \\ A_{i2} &= (\delta_2 + \beta_2 Pr GV_i) \\ A_{i3} &= (\gamma_3 + \alpha_3 Pr GU_i) \\ A_{i4} &= (\delta_4 + \beta_4 Pr GV_i) \\ D &= 0 \end{aligned} \right\} \tag{11}$$

where  $G = Gr^{1/2}$ ,  $\alpha$ ,  $\beta$ ,  $\gamma$  and  $\delta$  are functions of the local  $\Delta X$  and  $\Delta Y$  relative to the node point  $i$  and  $Pr$  is Prandtl number.

*Solution procedure*

The numerical solution procedure consists of cyclic Gauss–Seidel iterative computation on the set of SD representations of the governing equations (1)–(5), while imposing the respective boundary conditions for each equation in turn. The sequence is as follows:

- (i) A specification of  $H/B$  and  $C_{fi}$ , the geometric parameters, initialises the automatic mesh-generator which constructs and stores an appropriate solution grid.
- (ii) The main program picks up the energy equation (2) in the form of equation (10), imposes the set of temperature boundary condition equations ((7a), (7b) and (8a)) or ((7a), (7b) and (8b)), depending on whether Case I or Case II is specified. Then with an arbitrary initial temperature distribution (usually zero) within the domain and zero velocity at all the nodes, the energy equation is solved iteratively to convergence. This would be the pure conduction solution corresponding to  $Gr = 0$ .
- (iii) When a Grashof number,  $Gr > 0$  is specified,

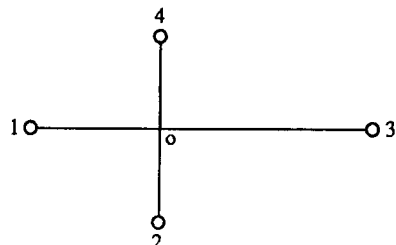


FIG. 2. Local node identification.

the wall velocities are retained as zero and the energy equation is solved in full as

$$\theta_i^{(k+1)} = \frac{1}{A_{i0}} (-A_{i1}\theta_i^{(k)} - A_{i2}\theta_{i2}^{(k)} - A_{i3}\theta_{i3}^{(k)} - A_{i4}\theta_{i4}^{(k)}) \tag{12}$$

using the convergence criterion,

$$|\theta_i^{k+1} - \theta_i^k| \leq 10^{-4}.$$

The converged temperature values  $\theta_{i-1,M}^{k+1}$  are stored separately as  $\theta_{i-1,M}^n$ , for later use in tests for global convergence.

(iv) The vorticity equation (1) is solved next. It requires wall vorticity  $\Omega_w$  for its solution. This is provided by using the latest computed values of  $U$  and  $V$  along the walls in equations (3) and (4) to obtain  $\Psi_i$  which is then used in equation (5) to obtain  $\Omega_w$  along the walls. After this, the interior values of  $\Omega_i$  are solved for iteratively, with the SD representation of equation (1), until convergence is obtained.

(v) The stream function equation is then solved. Boundary conditions are specified as  $\Psi = 0$  on all walls. Arbitrary initial distribution of  $\Psi = 0$  is effected on the interior and the SD representation of equation (5) is solved iteratively until convergence is obtained for  $\Psi$ .

(vi) The latest values of  $\Psi$  are used in equations (3) and (4) for direct computation of  $U$ - and  $V$ -velocity components, respectively.

(vii) Using current values of  $U$  and  $V$ , the computational procedure returns to step (iii) and the energy equation is solved once again. Local convergence of  $\theta$  now produces  $\theta_{i-1,M}^{n+1}$  which may then be compared with the previous  $\theta_{i-1,M}^n$  to determine global

convergence. If  $\theta_{i-1,M}^{n+1}$  and  $\theta_{i-1,M}^n$  meet the convergence criterion, a solution of the overall problem is deemed to have been achieved for the specified  $Gr$ , otherwise, the scheme moves down to step (iv), i.e. the solution of vorticity equation, after replacing  $\theta_{i-1,M}^n$  with  $\theta_{i-1,M}^{n+1}$ .

(viii) Whenever global convergence is achieved the local and mean Nusselt numbers  $Nu_x$  and  $\overline{Nu}_x$  are computed, respectively as

$$Nu_x = \left. \frac{\partial \theta}{\partial Y} \right|_{Y=0} \tag{13}$$

$$\overline{Nu}_x = \frac{1}{B} \int_0^B Nu_x \, dx. \tag{14}$$

The integration in equation (14) is carried out by a numerical trapezoidal integration sub-program.

Higher Grashof numbers require finer discretisation which creates more nodes. Thus, three different half-mesh sizes of  $15 \times 15$  (120 nodes),  $29 \times 29$  (435 nodes) and  $57 \times 57$  (1653 nodes) were used for a Grashof number range  $0 \leq Gr \leq 10^9$ , depending on the value of  $H/B$ .

**RESULTS AND DISCUSSION**

In the presentation of the distribution of the field variables and heat transfer characteristics, values of  $H/B = 0.25$  and  $C_{ri} = 0.33$  (i.e. circular segment) have been used. This choice is influenced by the relative ease of fabrication for both experimental and full scale applications. Also high Grashof numbers in the range  $10^6 \leq Gr \leq 10^9$  have been used in consideration of the

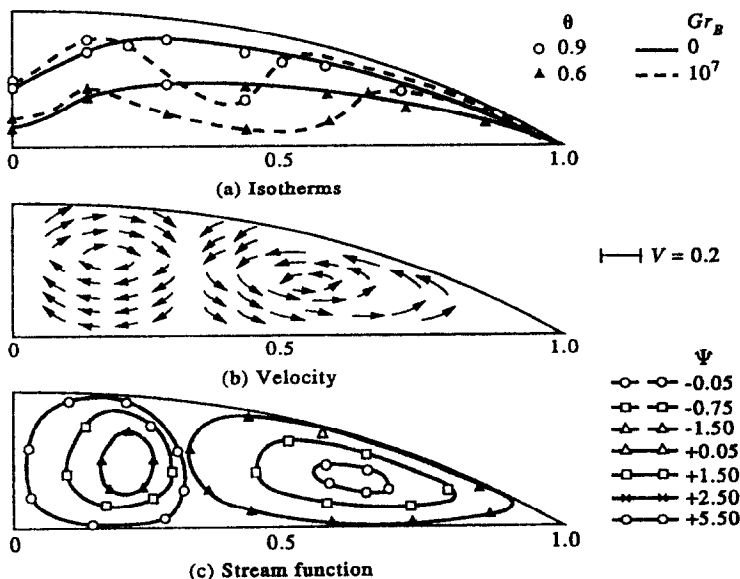


Fig. 3. Distribution of some field variables for the isothermal condition for  $H/B = 0.25$ ,  $C_{ri} = 0.33$  and  $Gr = 10^7$ .

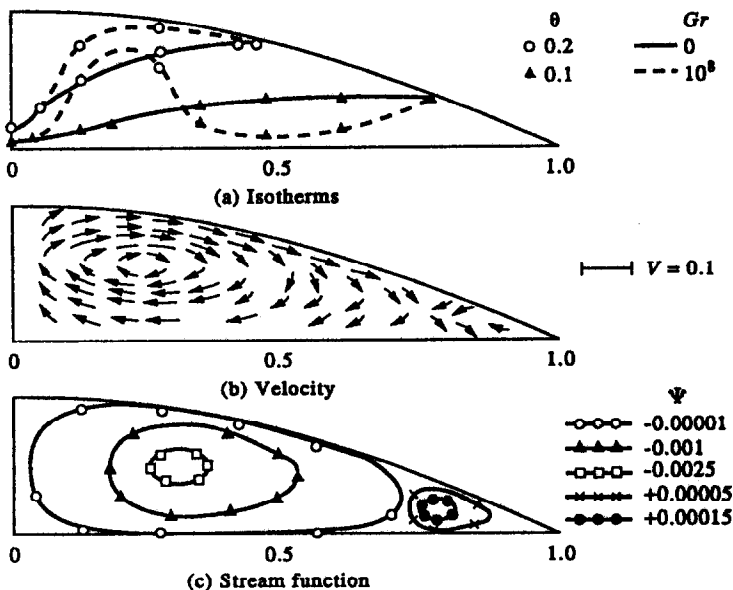


FIG. 4. Distribution of some field variables for the constant heat-flux condition for  $H/B = 0.25$  and  $C_{ft} = 0.33$  and  $Gr = 10^8$ .

practical applications discussed in the introduction. For example, it is estimated that an average solar heat flux of  $1 \text{ kW m}^{-2}$  reaches the earth's surface around noon each day and this translates to a Grashof number of about  $10^9$  for the constant heat flux case.

Figures 3(a)–(c) show the distribution of temperature, resultant velocity vector and stream function, respectively for  $H/B = 0.25$ ,  $C_{ft} = 0.33$  and  $Gr = 10^7$ .

Of interest is the remarkable contrast between the  $Gr = 0$  (pure conduction) and  $Gr = 10^7$  patterns in Fig. 3(a). This pattern is consistent with the dual streamline pattern of Fig. 3(c). Figures 4(a)–(c) are the constant heat-flux (Case II) versions of Figs. 3(a)–(c). A double-flow pattern also exists in this case but the magnitudes and positions of the patterns differ.

Figure 5 shows the local Nusselt number,  $Nu_x$  dis-

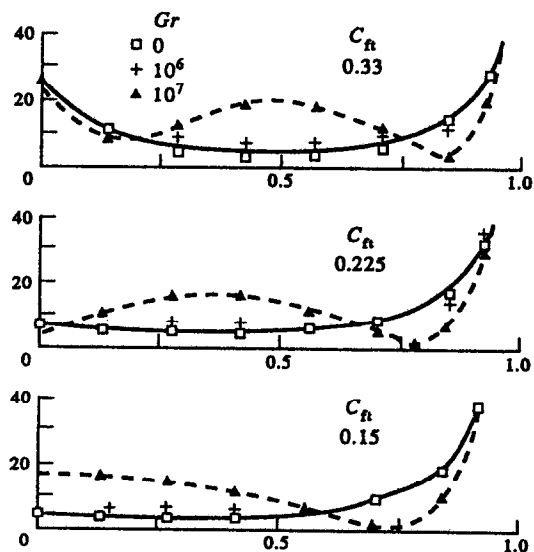


FIG. 5. Local Nusselt number,  $Nu_x$  distribution along cold wall for isothermal condition for  $H/B = 0.25$ .

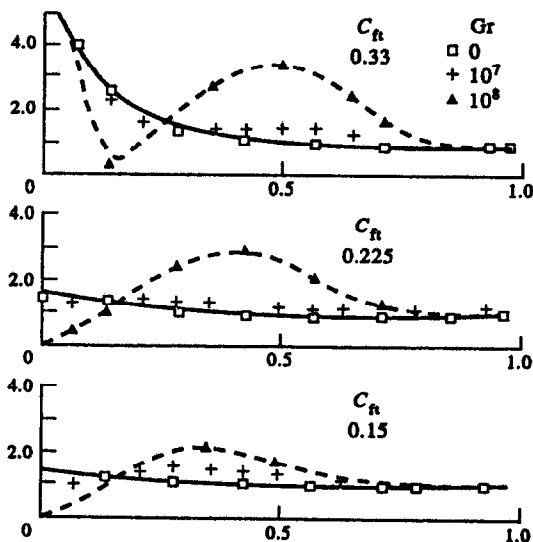


FIG. 6. Local Nusselt number,  $Nu_x$  distribution along the cold wall for the constant heat-flux condition for  $H/B = 0.25$ .

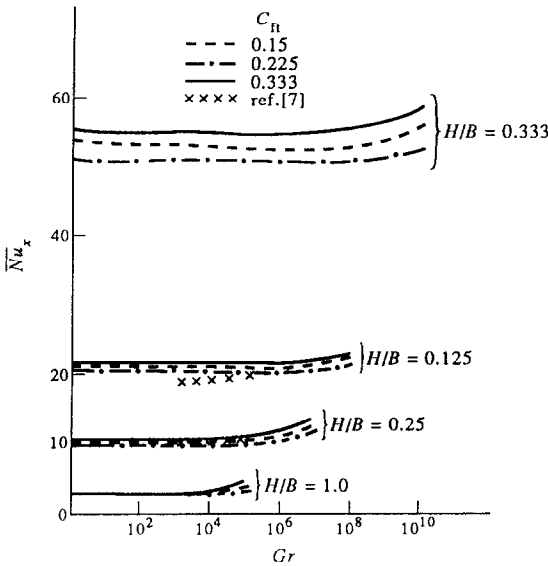


FIG. 7. Mean Nusselt number vs Grashof number for various concavity factors ( $0.15 \leq C_{fi} \leq 0.33$ ) and ( $0.05 \leq H/B \leq 1.0$ ) for isothermal hot-wall, Case I.

tribution along the cold wall for Case I, for  $C_{fi} = 0.33$ , 0.225 and 0.15, respectively. The local heat transfer rate is almost indistinguishable for  $Gr = 0$  and  $Gr = 10^6$ . However, a distinctive heat transfer pattern

emerges for  $Gr = 10^7$ . It is obvious from the patterns of Figs. 3 and 5 that the effects of convection currents become significant in the range  $Gr \geq 10^7$ . In the latter figure, one observes that a large fraction of the heat transfer is concentrated in the last one-third of the base. This condition is fairly consistent for all  $C_{fi}$ s considered. However, the fraction of the overall heat that is transferred through this  $\frac{1}{3}$  length depends on the  $Gr$  range. A similar heat transfer pattern has been reported by Akinsete and Coleman [7] and Talabi [21] for triangular geometries.

Figure 6 is the constant heat-flux version of local Nusselt number distribution. It is easily observable that the last  $\frac{1}{3}$  length does not have the concentrated heat-transfer of Case I but rather a relatively small value, mostly due to conduction.

Figures 7 and 8 are generalised plots of the mean Nusselt number as functions of Grashof number for Cases I and II, respectively, from which the general conclusions regarding heat transfer in parabolic enclosures can eventually be drawn. Some of the result data of ref. [7] have also been shown in Fig. 7 for  $C_{fi} = 0$ .

Finally, it would be instructive to compare the present results with some of those available for triangular enclosures and thus, draw some conclusion on their relative heat transfer characteristics.

(i) In the isothermal Case I, the heat transfer pat-

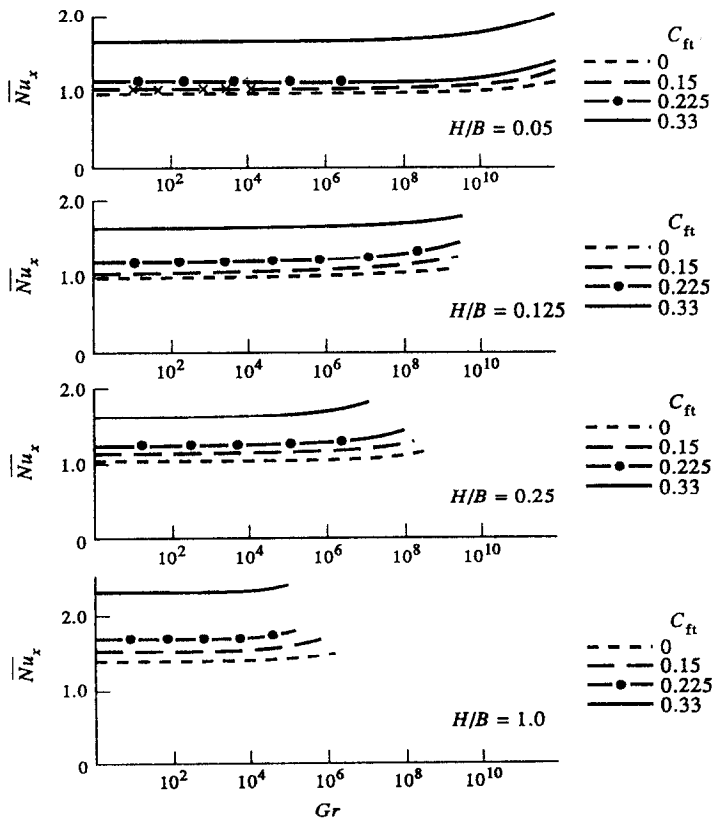


FIG. 8. Mean Nusselt number vs Grashof number for various concavity factors ( $0 \leq C_{fi} \leq 0.33$ ) and ( $0.05 \leq H/B \leq 1.0$ ) for constant heat-flux condition, Case II.

tern in the form of local Nusselt number  $Nu_x$  tends to be more uniformly distributed over the cold base for the parabolic section than the triangular section as reported by Akinsete and Coleman [7]. In the triangular case, the heat transfer rate is generally very high near the junction of the hot and cold walls. This pattern is similar to the ones obtained for the parabolic profiles at low Grashof number.

(ii) In the constant heat-flux Case II, the parabolic profile is seen to enhance convective heat transfer as may be observed from the higher overall heat-transfer rate along the cold wall in comparison to triangular profile. Besides, the local heat transfer rate is more uniform in Case II. In making the above two comparisons, the results of the most effective parabolic profile ( $C_{ft} = 0.33$ ) which corresponds to a circular profile has been used. Nevertheless, the other parabolic profiles ( $C_{ft} = 0.225, 0.15$ , etc) show similar trends as those of  $C_{ft} = 0.33$ .

(iii) For the isothermal case, the heat transfer to the cold wall as measured by the mean Nusselt number,  $\overline{Nu}_x$ , increases slightly with increase in  $Gr$  and  $Pr$  (Fig. 7) but decreases with increasing  $H/B$  and increasing  $C_{ft}$ , with the exception of  $C_{ft} = 0.33$ , which can be considered an anomaly. This latter geometric configuration has the highest  $\overline{Nu}_x$  next to  $C_{ft} = 0.15$  instead of the expected lowest. This is consistent for all the  $H/B$  considered in Case I (Fig. 7).

(iv) For the constant heat-flux configuration, the heat transfer rate,  $\overline{Nu}_x$ , increases with increasing  $Gr$ ,  $H/B$ ,  $C_{ft}$  (Fig. 8) and  $Pr$ .

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